Parameters	Range	Accuracy sensor input to DFDR readout	Sampling interval (per second)	resolution 4 read out
Main Gear Squat Switch Status.	Discrete		1	
Angle of Attack (if recorded directly).	As installed		2	0.3% 2.
Outside Air Temperature or Total Air Temperature.	-50 °C to +90 °C		0.5	0.3° c
Hydraulics, Each System Low Pressure.	Discrete		0.5	or 0.5% ² .
Groundspeed	As installed	Most accurate systems installed (IMS equipped aircraft only).	1	0.2% ² .

If additional recording capacity is available, recording of the following parameters is recommended. The parameters are listed in order of significance:

Drift Angle	When available. As installed.	As installed	4	
Wind Speed and Direction	When available. As installed.	As installed	4	
Latitude and Longitude	When available. As installed.	As installed	4	
Brake pressure/Brake pedal position.	As installed	As installed	1	
Additional engine parameters:				
EPR	As installed	As installed	1 (per engine)	
N ¹	As installed	As installed	1 (per engine)	
N ²	As installed	As installed	1 (per engine)	
EGT	As installed	As installed	1 (per engine)	
Throttle Lever Position	As installed	As installed	1 (per engine)	
Fuel FlowTCAS:	As installed	As installed	1 (per engine)	
TA	As installed	As installed	1	
RA	As installed	As installed		
Sensitivity level (as se- lected by crew).	As installed	As installed		
GPWS (ground proximity warning system).	Discrete		1	
Landing gear or gear selector position.	Discrete		0.25 (1 per 4 seconds).	
DME 1 and 2 Distance	0–200 NM;	As installed	0.25	1mi.
Nav 1 and 2 Frequency Selection.	Full range	As installed	0.25.	

[Doc. No. 25530, 53 FR 26153, July 11, 1988; 53 FR 30906, Aug. 16, 1988]

APPENDIX E TO PART 135—HELICOPTER FLIGHT RECORDER SPECIFICATIONS

		Accuracy sensor input to	Sampling inter-	Resolution 2
Parameters	Range	DFDR readout	val (per second)	read out
Time (GMT)	24 Hrs	±0.125% Per Hour	0.25 (1 per 4 seconds).	1 sec
Altitude	 1,000 ft to max certificated altitude of aircraft. 	±100 to ±700 ft (See Table 1, TSO-C51a).	1	5' to 30'.
Airspeed	As the installed meas- uring system.	±3%	1	1 kt
Heading	360°	±2°	1	0.5°.
Normal Acceleration (Vertical)	-3g to +6g	±1% of max range excluding datum error of ±5%.	8	0.01g
Pitch Attitude	±75°	±2°	2	0.5°
Roll Attitude	±180°	±2°	2	0.5°.
Radio Transmitter Keying	On-Off (Discrete)		1	0.25 sec
Power in Each Engine: Free	0-130% (power Turbine	±2%	1 speed 1	0.2% 1 to 0.4% 1
Power Turbine Speed and	Speed) Full range		torque (per	
Engine Torque.	(Torque).		engine)."	

¹ When altitude rate is recorded. Altitude rate must have sufficient resolution and sampling to permit the derivation of altitude to 5 feet.

2 Per cent of full range.

3 For airplanes that can demonstrate the capability of deriving either the control input on control movement (one from the other) for all modes of operation and flight regimes, the "or" applies. For airplanes with non-mechanical control systems (fly-by-wire) the "and" applies. In airplanes with split surfaces, suitable combination of inputs is acceptable in lieu of recording each surface separately.

4 This column applies to aircraft manufactured after October 11, 1991.

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Parameters	Range	Accuracy sensor input to DFDR readout Sampling val (per se		Resolution ² read out
Main Rotor Speed	0–130%	±2%	2	0.3% 1
Altitude Rate	±6,000 ft/min			0.2% 1
Pilot Input—Primary Controls (Collective, Longitudinal Cyclic, Lateral Cyclic, Pedal) ³ .	Full range	±3%	2	0.5% 1
Flight Control Hydraulic Pressure Low.	Discrete, each circuit		1	
Flight Control Hydraulic Pres- sure Selector Switch Posi- tion, 1st and 2nd stage.	Discrete		1	
AFCS Mode and Engagement Status.	Discrete (5 bits nec- essary).		1	
Stability Augmentation System Engage.	Discrete		1	
SAS Fault Status	Discrete		0.25	
Main Gearbox Temperature Low.	As installed	As installed	0.25	0.5% 1
Main Gearbox Temperature High.	As installed	As installed	0.5	0.5% 1
Controllable Stabilator Position.	Full Range	±3%	2	0.4% 1.
Longitudinal Acceleration	±1g	±1.5% max range excluding datum error of ±5%.	4	0.01g.
Lateral Acceleration	±1g	±1.5% max range excluding datum of ±5%.	4	0.01g.
Master Warning	Discrete		1	
Nav 1 and 2 Frequency Selection.	Full range	As installed	0.25	
Outside Air Temperature	−50 °C to +90 °C	±2° c	0.5	0.3° c

[Doc. No. 25530, 53 FR 26154, July 11, 1988; 53 FR 30906, Aug. 16, 1988; Amdt. 135–113, 73 FR 12571, Mar. 7, 2008; 73 FR 15281, Mar. 21, 2008; Amdt. 135–121, 75 FR 17047, Apr. 5, 2010]

APPENDIX F TO PART 135—AIRPLANE FLIGHT RECORDER SPECIFICATION

The recorded values must meet the designated range, resolution and accuracy requirements during static and dynamic conditions. Dynamic condition means the parameter is experiencing change at the maximum rate attainable, including the maximum rate of reversal. All data recorded must be correlated in time to within one second.

Parameters	Range	Accuracy (sensor input)	Seconds per sampling interval	Resolution	Remarks
Time or Relative Time Counts ¹ .	24 Hrs, 0 to 4095.	±0.125% Per Hour.	4	1 sec	UTC time preferred when available. Counter increments each 4 seconds of system operation.
Pressure Altitude.	- 1000 ft to max certificated alti- tude of aircraft. +5000 ft.	±100 to ±700 ft (see table, TSO C124a or TSO C51a).	1	5′ to 35″	Data should be obtained from the air data computer when practicable.
 Indicated air- speed or Cali- brated airspeed. 	50 KIAS or minimum value to Max V _{so+} and V _{so} to 1.2 V _{.D} .	±5% and ±3%	1	1 kt	Data should be obtained from the air data computer when practicable.
Heading (Primary flight crew reference).	0 – 360° and Discrete "true" or "mag".	±2°	1	0.5°	When true or magnetic head- ing can be selected as the primary heading reference, a discrete indicating selec- tion must be recorded.
 Normal Acceleration (Vertical) 9. 	-3g to +6g	±1% of max range exclud- ing datum error of ±5%.	0.125	0.004g	
6. Pitch Attitude	±75%	±2°	1 or 0.25 for air- planes oper- ated under § 135.152(j).	0.5°	A sampling rate of 0.25 is recommended.

 ¹ Per cent of full range.
 ² This column applies to aircraft manufactured after October 11, 1991.
 ³ For all aircraft manufactured on or after December 6, 2010, the sampling interval per second is 4.